

NSE Phase stability

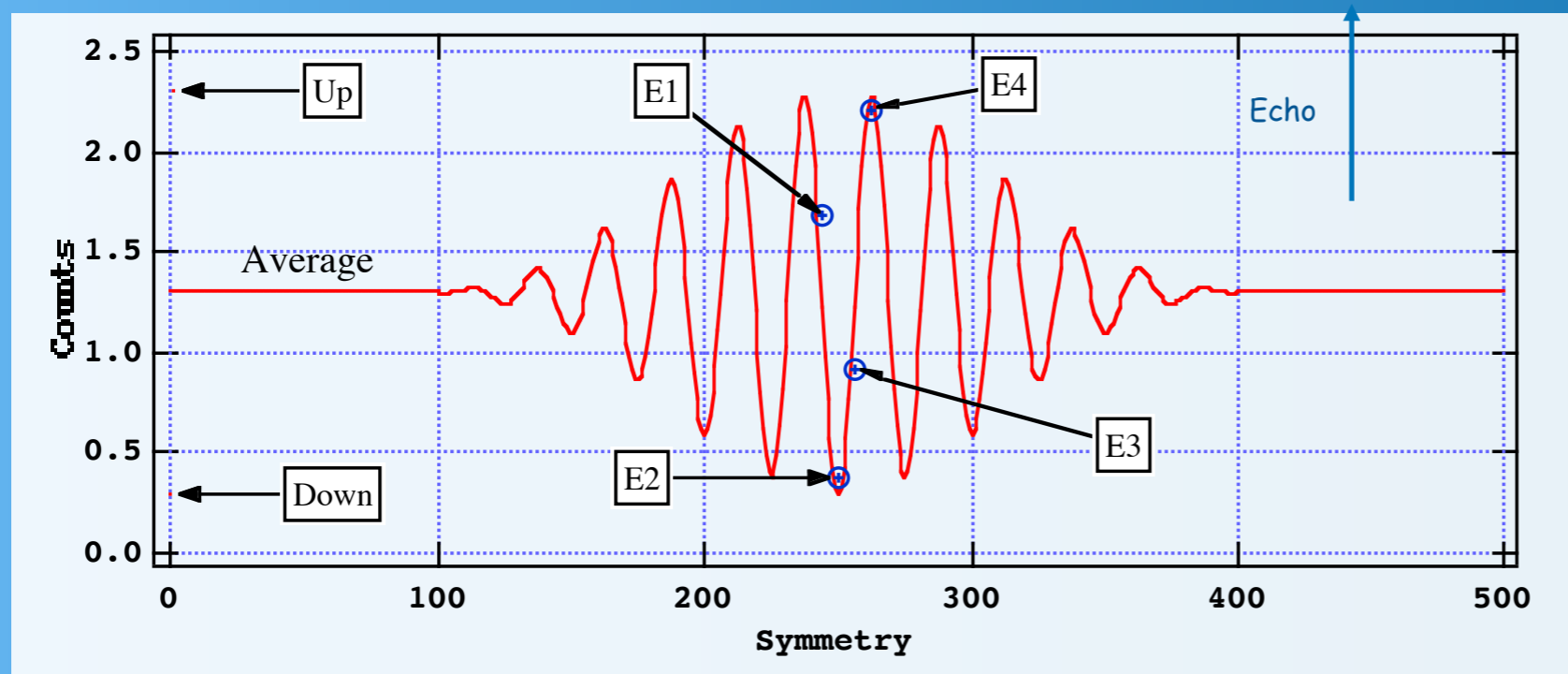
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How echo measured

We measure polarized intensity versus field integral difference

We could fit Echo, Average, frequency, phase

$$\text{Counts} = \text{Aver} + \text{Echo} * \sin(\text{I} - \text{phase} / \text{frequency})$$



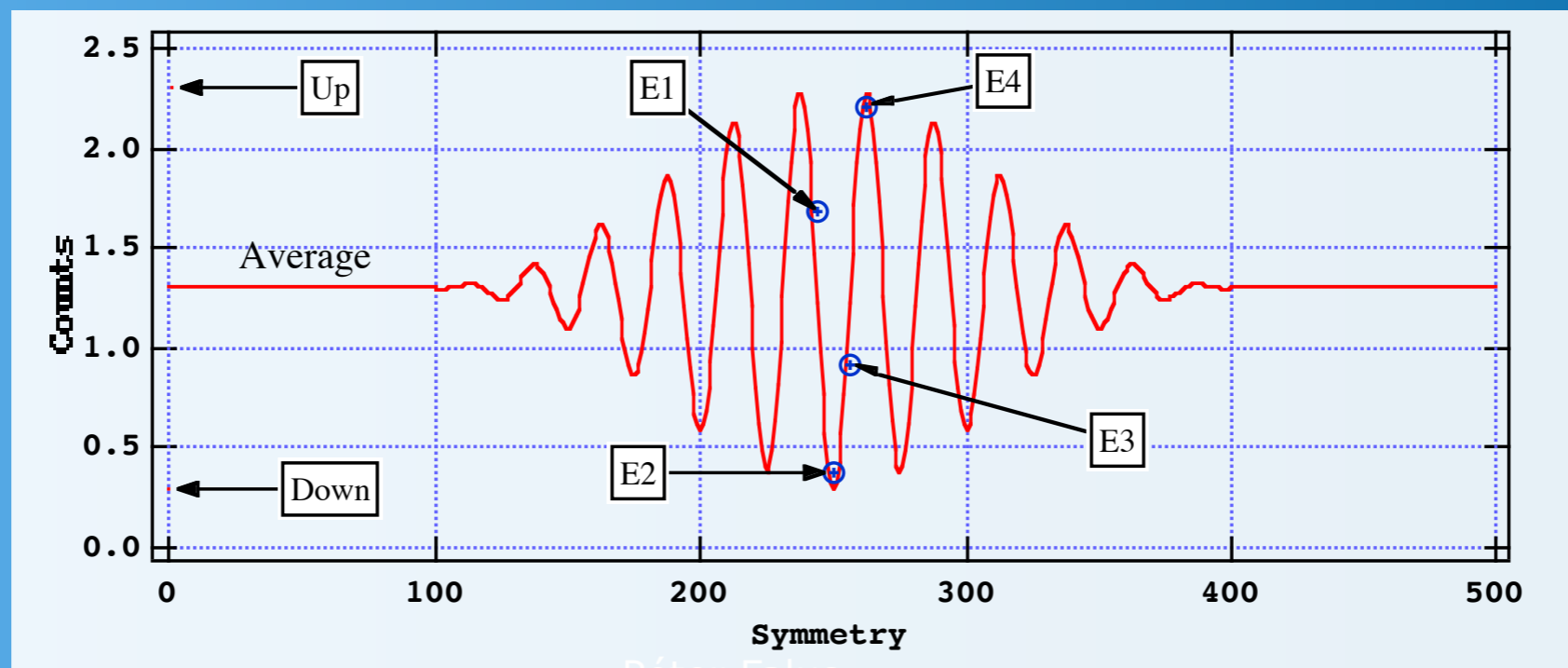
$$\begin{aligned} E1 &= \text{Aver} + \text{Echo} * \sin(\phi) \\ E2 &= \text{Aver} - \text{Echo} * \cos(\phi) \\ E3 &= \text{Aver} - \text{Echo} * \sin(\phi) \\ E4 &= \text{Aver} + \text{Echo} * \cos(\phi) \end{aligned}$$

Do we need phase ?

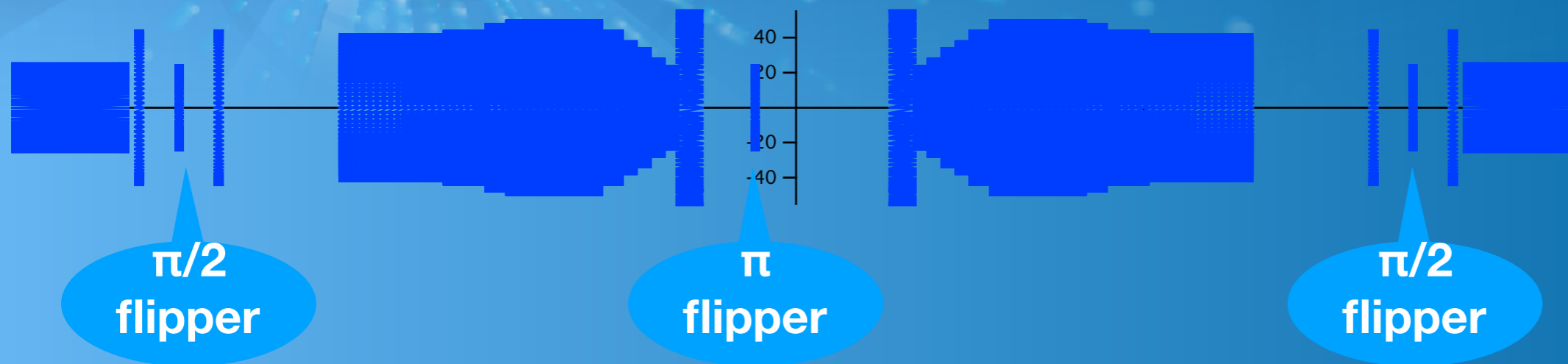
We need echo, know average and frequency fit echo amplitude and phase throw phase way

EXCEPT

- We need the phase to measure speed
- We want to keep resolution stable
- We measure echo close to 0
- We optimize count times



What is Phase ?



$$\Delta = \int_1 B d\ell - \int_2 B d\ell$$

Field integral difference:
 difference in field or in physical length
 We assure 0 difference by SYMMETRY

How much phase difference can we tolerate

We measure $\langle \cos \varphi \rangle$ 

$\cos(18^\circ) = 0.95$ 5% loss if phases within $\pm 18^\circ$
Attention $\cos()$ is quadratic around 0!

Sidebar, subtle: Phase shift during measurement or field integral difference between trajectories will have the same effect; echo loss, same criteria apply.

Field Stability example

We have two 1000 turn solenoids. We need 1,000,100 Amperturns in one coil and 1,000,000 in another. The difference should be stable to 0.1 Amperturn precision

Solution 1: Coil 1 supplied by 1,000.1 A Coil 2 supplied by 1,000A from another supply. Required precision 10^{-7}

Solution 2: Both coils are supplied by 1000A from the same supply, they are in series. We wind 100 extra turns on coil 1 and supply it with 1A. Required precision: no requirement on big supply, 10^{-3} on small supply.

The statement which is a question:

In resonant NSE when geometry determines the field integral, 1% flipper distance change results in 1% field integral change

For classic flippers we have to integrate the field at the flipper position with displacement. Since typically on the flipper we have 100-300x less field than in the precession region, field integral change is 300 times less. They are less sensitive to flipper position/flatness.

